Newton–Okounkov polytopes of symplectic flag varieties

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0. Toric geometry Newton (or moment) polytopes

1. Representation theory

Gelfand–Zetlin polytopes and *string polytopes* (Berenstein–Zelevinsky, Littelmann, 1998)

2. Algebraic geometry

Newton–Okounkov convex bodies (Kaveh–Khovanskii, Lazarsfeld–Mustata, 2009)

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Toric varieties

Theory of Newton polytopes

To every smooth projective toric variety X^n there corresponds a simple convex lattice polytope $\Delta(X) \subset \mathbb{R}^n$.

Geometry of $X \leftrightarrow$ combinatorics of $\Delta(X)$

Faces F of $\Delta(X)$ are in bijection with closures of torus orbits \mathcal{O}_F in X.

Intersection theory

$$\mathcal{O}_F \cdot \mathcal{O}_E = \mathcal{O}_{F \cap E}$$

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Non-toric varieties

Theory of Newton-Okounkov convex bodies

To every projective variety X^n there corresponds a convex body $\Delta_v(X) \subset \mathbb{R}^n$ (it depends not only on X but also on a valuation v on $\mathbb{C}(X)$). In many cases of interest (e.g. for spherical varieties) it is a convex lattice polytope.

Main property of $\Delta_v(X)$

 $\deg X = n! \text{volume}(\Delta_v(X))$

Question

Is there a useful relation between intersection theory on X and intersection of faces of $\Delta_{\nu}(X)$ (when $\Delta_{\nu}(X)$ is a polytope)?

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Motivating example: flag varieties

Definition

The *flag variety* X is the variety of complete flags in \mathbb{C}^n :

$$X = \{\{0\} = V^0 \subset V^1 \subset \ldots \subset V^{n-1} \subset V^n = \mathbb{C}^n \mid \dim V^i = i\}$$

Remark

Alternatively, $X = GL_n(\mathbb{C})/B$, where B denotes the group of upper-triangular matrices (*Borel subgroup*). In this form, the definition can be extended to arbitrary connected reductive groups.

Schubert varieties

$$X_w = \overline{BwB/B}, \ w \in S_n$$

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give basis in $H^*(X,\mathbb{Z})$.

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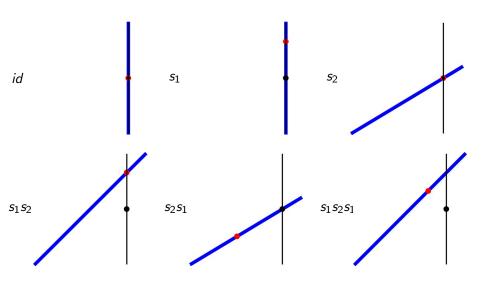
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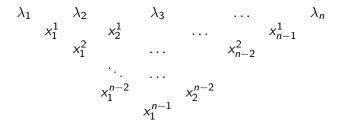
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Schubert varieties for GL_3/B .



Gelfand–Zetlin polytopes

The Gelfand–Zetlin polytope Δ_{λ} is defined by inequalities:

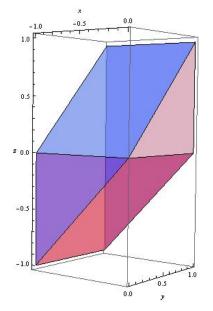


where $(x_1^1, \ldots, x_{n-1}^1; \ldots; x_1^{n-1})$ are coordinates in \mathbb{R}^d , and the notation

a b c

means a < c < b.

Gelfand-Zetlin polytopes

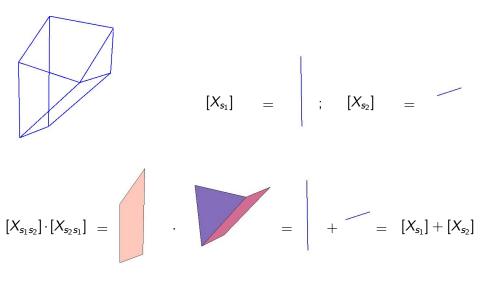


A Gelfand–Zetlin polytope for *GL*₃:

$$\begin{array}{cccc}
-1 & 0 & 1 \\
 & x & y \\
 & z
\end{array}$$

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Schubert calculus and Gelfand-Zetlin polytopes



Results

- Relation between Schubert varieties and preimages of rc-faces of Δ_{λ} under the Guillemin-Sternberg moment map $X \to \Delta_{\lambda}$ (Kogan, 2000)
- Degenerations of Schubert varieties to (reducible) toric varieties given by (unions of) faces of Δ_{λ} (Kogan–E.Miller, Knutson–E.Miller, 2003)
- Description of H^{*}(X, Z) using volume polynomial of Δ_λ (Kaveh, 2011)
- Schubert calculus: intersection product of Schubert cycles in $H^*(X,\mathbb{Z})$ = intersection of faces in Δ_{λ} (K.-Smirnov-Timorin, 2012)

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Generalized flag varieties

Let G be an arbitrary connected reductive group, and X = G/B the complete flag variety.

Question

Which polytopes are best suited for Schubert calculus on G/B?

Polytopes

Generalizatons of Gelfand–Zetlin polytopes from *GL_n* to *G* include *string polytopes*, Newton–Okounkov polytopes of flag varieties, and polytopes constructed via convex-geometric divided difference operators (K., 2013).

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Valuation

Let $X^n \subset \mathbb{P}^N$ be a projective subvariety with coordinates (x_1, \ldots, x_n) in a neighborhood of a smooth point $p \in X$. Define the valuation $v : \mathbb{C}(X) \to \mathbb{Z}^n$ by sending every polynomial $f(x_1, \ldots, x_n)$ to (k_1, \ldots, k_n) where $x_1^{k_1} \cdots x_n^{k_n}$ is the lowest degree term in f (assuming that $x_1 \succ x_2 \succ \ldots \succ x_n$).

Vector space

Let $V \subset \mathbb{C}(X)$ be the vector space spanned by restrictions to $X \subset \mathbb{P}^N$ of linear functions on

Example

If $X = \nu_N(\mathbb{P}^1) = \{(y_0^N : y_1y_0^{N-1} : \ldots : y_1^N)\} \subset \mathbb{P}^N$ and $x_1 = \frac{y_1}{y_0}$, then v(f) = the order of zero (or pole) of f at p and $V = \langle 1, x_1, \ldots, x_1^N \rangle$.

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Naive definition

The Newton-Okounkov polytope $\Delta_{v}(X) \subset \mathbb{R}^{n}$ of X^{n} is the convex hull of v(f) for all $f \in V$.

Example $\Delta_{\nu}(\nu_{\mathcal{N}}(\mathbb{P}^{1})) = [0, \mathcal{N}] \subset \mathbb{R}^{1}$

Example

A toric variety X^n has a natural system of coordinates (x_1, \ldots, x_n) coming from $(\mathbb{C}^*)^n \subset X^n$. For a projective embedding $X^n \subset \mathbb{P}^N$, the space V is spanned by monomials in x_1, \ldots, x_n . Hence, the valuation v does not matter, and $\Delta_v(X^n)$ is always the Newton polytope of X.

Observation

If n!volume $(\Delta_v(X)) = \deg(X)$, then the naive definition coincides with the correct definition.

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If n!volume $(\Delta_{\nu}(X)) = \deg(X)$, then the naive definition coincides with the correct definition.

Coordinates on the open Schubert cell

If the flag $(a \in I \subset \mathbb{P}^2)$ is in general position with a fixed flag $(a_0 \in I_0 \subset \mathbb{P}^2)$, then $I \cap I_0 = a' \neq a_0$ and $a \notin I_0$. Hence,

$$\mathsf{a}'=(x:1:0); \quad \mathsf{I}=\langle \mathsf{a}',(y:0:1)
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are coordinates (assuming that $a_0 = (1:0:0)$, $l_0 = \{(\star:\star:0)\}$).

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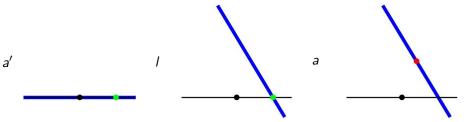
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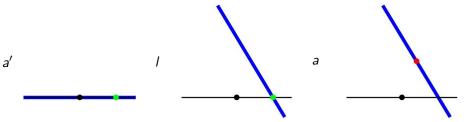


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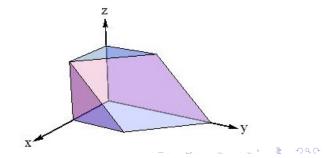
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$$\begin{pmatrix} xz+y & z & 1 \end{pmatrix} \times \begin{pmatrix} 1 \\ -x \\ -y \end{pmatrix} = \begin{pmatrix} xz+y & -x^2z - xy & -xyz - y^2 \\ z & -xz & -yz \\ 1 & -x & -y \end{pmatrix}$$

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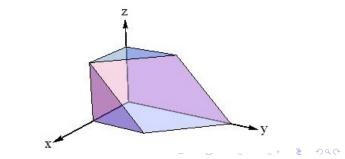
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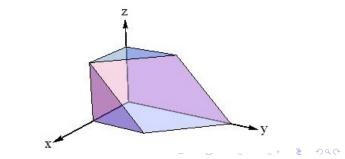
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Consider the embedding $p: GL_3/B \hookrightarrow \mathbb{P}^2 \times (\mathbb{P}^2)^* \hookrightarrow \mathbb{P}^8$; $p: (a, l) \mapsto a \times l$. Then p takes the flag with coordinates (x, y, z) to

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Valuations on $\mathbb{C}(G/B)$

Decomposition of w₀

Fix a reduced decomposition $\overline{w_0} = s_{i_1} \dots s_{i_d}$ of the longest element w_0 in the Weyl group of G.

Flag of Schubert varieties

Choose coordinates compatible with the flag $X_{id} \subset X_{s_{i_d}} \subset X_{s_{i_d-1}s_{i_d}} \subset \ldots \subset X_{s_{i_2}\cdots s_{i_d}} \subset X$ (coordinates "at infinity").

Flag of translated Schubert varieties

Choose coordinates compatible with the flag $w_0 X_{id} \subset s_{i_1} \dots s_{i_{d-1}} X_{s_{i_d}} \subset s_{i_1} \dots s_{i_{d-2}} X_{s_{i_{d-1}} s_{i_d}} \subset \dots \subset s_{i_1} X_{s_{i_2} \dots s_{i_d}} \subset X$ (coordinates at the open Schubert cell).

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Generalized Gelfand-Zetlin polytopes

(Okounkov, 1998)

The symplectic Gelfand-Zetlin polytope coincides with the Newton-Okounkov polytopes of Sp_{2n}/B for the lowest order term valuation v associated with the flag of Schubert varieties for $\overline{w_0} = (s_1)(s_2s_1s_2)\dots(s_ns_{n-1}\dots s_2s_1s_2\dots s_{n-1}s_n).$

(Kaveh, 2013)

The string polytopes associated with $\overline{w_0}$ coincide with the Newton–Okounkov polytopes of X for the highest order term valuation v associated with the flag of Schubert varieties for $\overline{w_0}$.

Example

If $G = GL_n$ and $\overline{w_0} = s_1(s_2s_1)\cdots(s_{n-1}\cdots s_1)$ then the corresponding string polytopes are exactly Gelfand–Zetlin polytopes.

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String polytopes

(J.Miller, 2014)

Newton-Okounkov polytopes of Schubert varieties can be represented by unions of faces of a given string polytope.

Remark

This is an existence result. Explicit descriptions of such faces are so far known in the case of GL_n , $\overline{w_0} = s_1(s_2s_1)\cdots(s_{n-1}\cdots s_1)$ (K.–Smirnov–Timorin, 2012) and Sp_4 , $\overline{w_0} = s_1s_2s_1s_2$ (Ilyukhina, 2012).

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Find an efficient algorithm for representing Schubert cycles explicitly by unions of faces.

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Mitosis

Combinatorial mitosis on pipe-dreams for GL_n

Pipe-dreams corresponding to permutation w can be obtained from pipe-dreams corresponding to permutation $s_i w$ (if $I(s_i w) < I(w)$) by an explicit combinatorial algorithm (Knutson–E.Miller, 2003).

Mitosis on parallelepipeds

Basic steps of mitosis on pipe-dreams admit a geometric realization (mitosis on parallelepipeds) compatible with the action of Demazure operators (K.-Smirnov-Timorin, 2012).

Geometric mitosis

If Gelfand–Zetlin polytope is replaced by a DDO polytope for another reductive group (e.g. for Sp(2n)) then mitosis on parallelepipeds still works and produces a new combinatorial algorithm (K., 2014).

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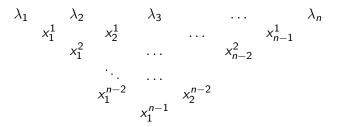
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Gelfand-Zetlin polytope



has (n-1) different fibrations by coordinate parallelepipeds. Hence, there are (n-1) different mitosis operations on its faces.

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(K., 2013)

Take $\overline{w_0} = s_2 s_1 s_2 s_1$. The corresponding DDO polytope Q_λ is given by inequalities

$$\begin{split} 0 &\leq x \leq \lambda_1, \quad z \leq x + \lambda_2, \quad y \leq 2z, \\ y &\leq z + \lambda_2, \quad 0 \leq t \leq \lambda_2, \quad t \leq \frac{y}{2}. \end{split}$$

(K., 2014)

The polytopes Q_{λ} coincide with the Newton–Okounkov polytopes of Sp_4/B for the lowest order term valuation v associated with the flag of subvarieties $w_0X_{id} \subset s_1s_2s_1X_{s_2} \subset s_1s_2X_{s_1s_2} \subset s_1X_{s_2s_1s_2} \subset X$.

Remark

The polytopes Q_{λ} have 11 vertices so they are not combinatorially equivalent to string polytopes (=symplectic Gelfand–Zetlin polytopes) associated with $s_2s_1s_2s_1$ or $s_1s_2s_1s_2r_1 \cdot e_{r_1} \cdot e_{r_2} \cdot e$

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Skew pipe-dreams

Faces that contain the lowest vertex $a_{\lambda} = (0, 0, 0, 0)$ can be encoded by the diagrams:

$$+ \iff 0 = t$$
$$+ \iff 0 = x + \iff t = \frac{y}{2}$$
$$+ \iff y = 2z$$

Parallelepipeds

The polytope Q_{λ} admits two different fibrations (by translates of xy- and zt-planes), hence, there are two mitosis operations M_1 and M_2 on faces of Q_{λ} .

Isotropic flags

 $Sp_4/B = \{ (V^1 \subset V^2 \subset V^3 \subset \mathbb{C}^4) \mid \omega \mid_{V^2} = 0, V^1 = V^{3\perp} \} = \{ (a \in I \subset \mathbb{P}^3) \mid I - \text{ isotropic line } \}$

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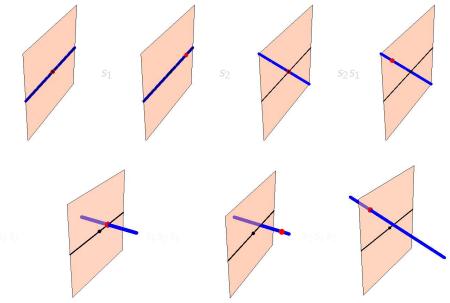
$$\begin{array}{c} + \Longleftrightarrow 0 = t \\ + \Longleftrightarrow 0 = x & + \Leftrightarrow t = \frac{y}{2} \\ + \iff y = 2z \end{array}$$

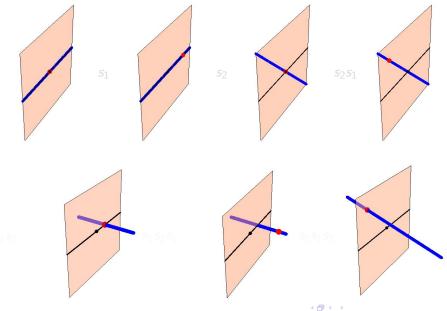
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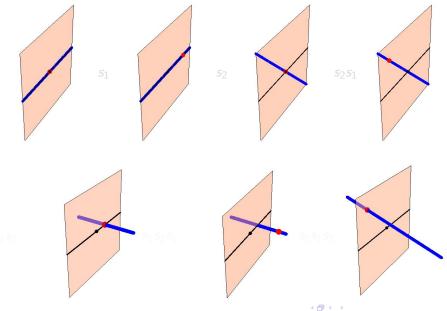
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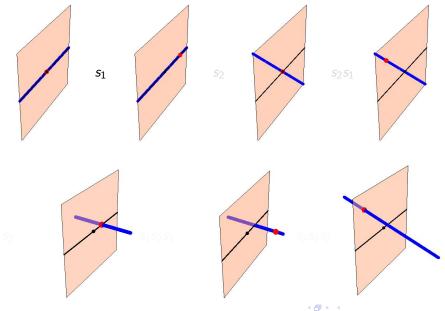
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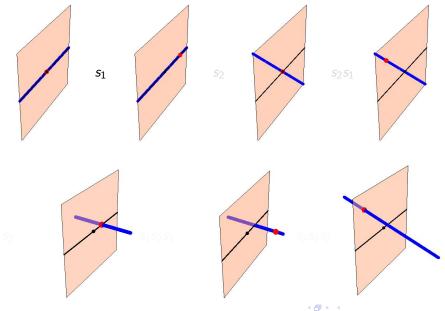
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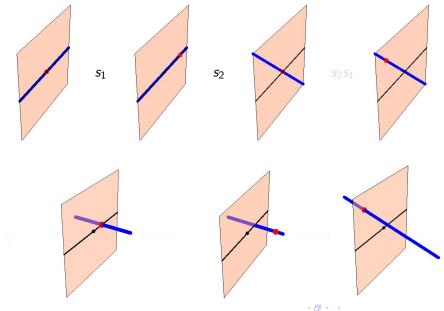


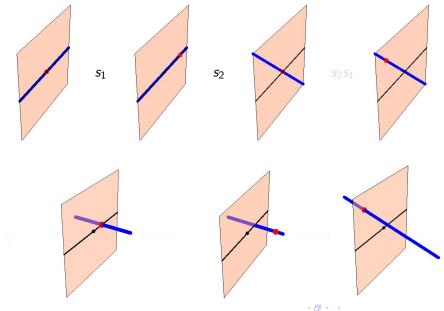


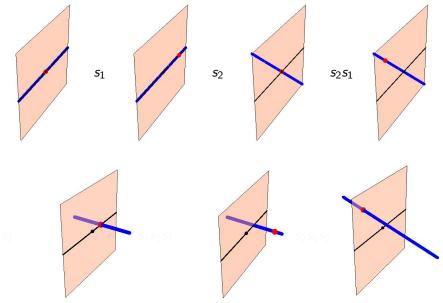




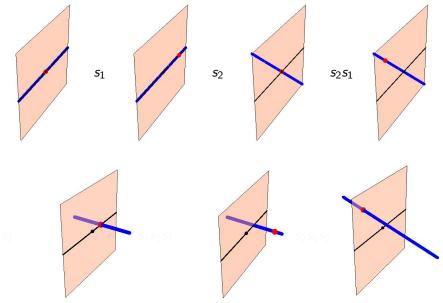




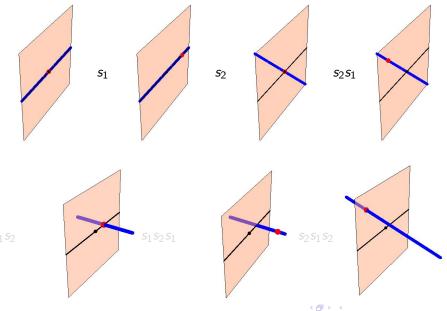


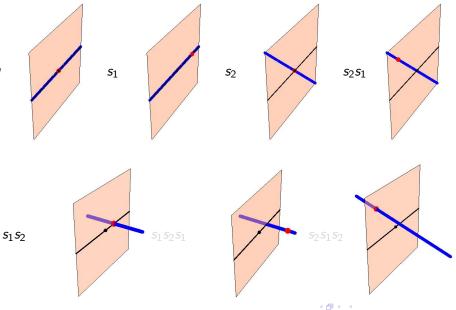


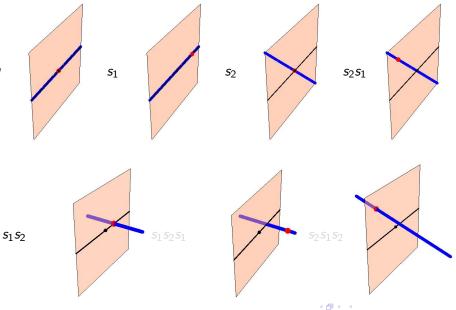
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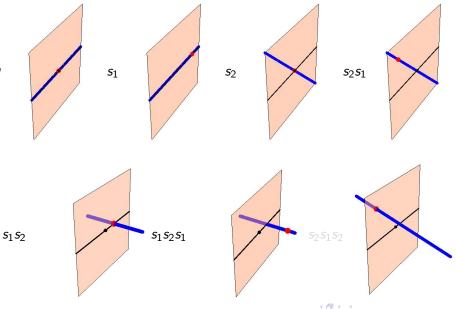


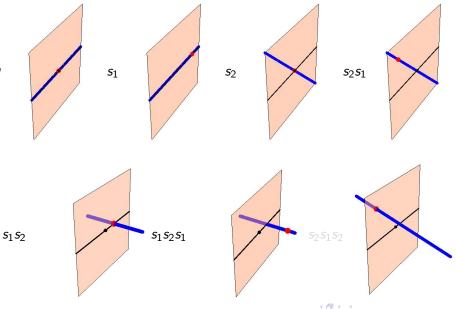
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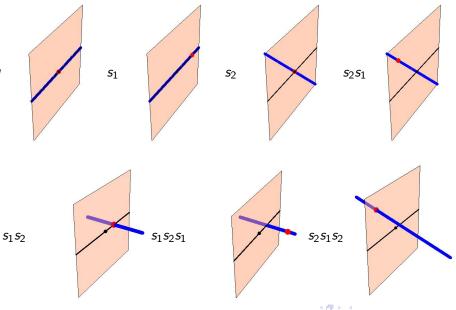


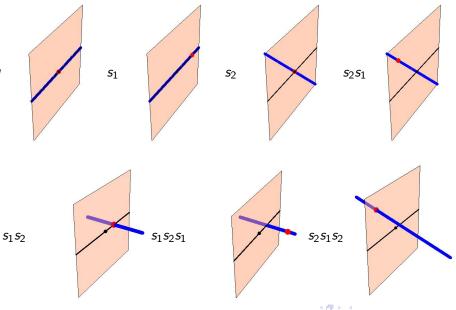


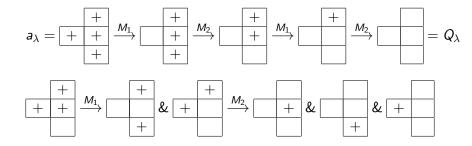












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